

The predictability of band-limited, high-frequency and mixed processes in the presence of ideal low-pass filters

This article has been downloaded from IOPscience. Please scroll down to see the full text article. 2008 J. Phys. A: Math. Theor. 41 382002 (http://iopscience.iop.org/1751-8121/41/38/382002) View the table of contents for this issue, or go to the journal homepage for more

Download details: IP Address: 171.66.16.150 The article was downloaded on 03/06/2010 at 07:11

Please note that terms and conditions apply.

J. Phys. A: Math. Theor. 41 (2008) 382002 (7pp)

doi:10.1088/1751-8113/41/38/382002

FAST TRACK COMMUNICATION

The predictability of band-limited, high-frequency and mixed processes in the presence of ideal low-pass filters

Nikolai Dokuchaev

Department of Mathematics, Trent University, Ontario, Canada

Received 13 March 2008, in final form 20 July 2008 Published 22 August 2008 Online at stacks.iop.org/JPhysA/41/382002

Abstract

Pathwise predictability of continuous-time processes is studied in a deterministic setting. We discuss uniform prediction in some weak sense with respect to certain classes of inputs. More precisely, we study the possibility of approximation of convolution integrals over future time by integrals over past time. We found that all band-limited processes are predictable in this sense as well as high-frequency processes with zero energy at low frequencies. It follows that a process of mixed type can still be predicted if an ideal low-pass filter exists for this process.

PACS numbers: 02.30.Mv, 02.30.Nw, 02.30.Yy, 07.05.Mh, 07.05.Kf Mathematics Subject Classification: 60G25, 93E10, 42B30

1. Introduction

We study pathwise predictability of continuous-time processes in a deterministic setting. It is well known that certain restrictions on the frequency distribution can ensure additional opportunities for prediction and interpolation of the processes. The classical result is the Nyquist–Shannon–Kotelnikov interpolation theorem for the low-band processes. There are related predictability results for the low-band processes (see, e.g., Wainstein and Zubakov (1962), Beutler (1966), Brown (1969), Slepian (1978), Knab (1981), Papoulis (1985), Marvasti (1986), Vaidyanathan (1987) and Lyman *et al* (2000, 2001)).

In the present paper, we study a special kind of weak predictability such that convolution integrals over future times can be approximated by convolution integrals over past times representing historical observations. We found some cases when this approximation can be made uniformly over a wide class of input processes. We found that all band-limited processes are predictable in this sense. A similar result is obtained for high-frequency processes. For the processes of mixed type, we found that a similar predictability can be achieved when the model allows a low-pass filter that acts as an ideal low-pass filter for this process. These results can be a useful addition to the existing theory of band-limited processes. The novelty is that we consider predictability of both high-frequency and band-limited processes in a weak sense

1751-8113/08/382002+07\$30.00 © 2008 IOP Publishing Ltd Printed in the UK

uniformly over classes of input processes. In addition, we suggest a new type of predictor. Its kernel is given explicitly in the frequency domain.

2. Definitions

Let \mathbb{I} denote the indicator function, $\mathbf{R}^+ \stackrel{\scriptscriptstyle \Delta}{=} [0, +\infty), \mathbf{C}^+ \stackrel{\scriptscriptstyle \Delta}{=} \{z \in \mathbf{C} : \operatorname{Re} z > 0\}, i = \sqrt{-1}.$

For complex-valued functions $x \in L_1(\mathbf{R})$ or $x \in L_2(\mathbf{R})$, we denote by $X = \mathcal{F}x$ the function defined on i**R** as the Fourier transform of *x*:

$$(\mathcal{F}x)(\mathrm{i}\omega) = \int_{-\infty}^{\infty} \mathrm{e}^{-\mathrm{i}\omega t} x(t) \,\mathrm{d}t, \qquad \omega \in \mathbf{R}.$$

If $x \in L_2(\mathbf{R})$, then X is defined as an element of $L_2(\mathbf{R})$.

For $v(\cdot) \in L_2(\mathbf{R})$ such that v(t) = 0 for t < 0, we denote by $\mathcal{L}v$ the Laplace transform:

$$V(p) = (\mathcal{L}v)(p) \stackrel{\scriptscriptstyle \Delta}{=} \int_0^\infty e^{-pt} v(t) \, \mathrm{d}t, \qquad p \in \mathbf{C}^+.$$
(2.1)

Let H^r be the Hardy space of holomorphic on \mathbb{C}^+ functions h(p) with a finite norm $\|h\|_{H^r} = \sup_{s>0} \|h(s + i\omega)\|_{L_r(\mathbb{R})}, r \in [1, +\infty]$ (see, e.g., Duren (1970)).

Let $\Omega > 0$ be given.

Definition 1. Let \mathcal{K} be the class of functions $k : \mathbf{R} \to \mathbf{R}$ such that k(t) = 0 for t > 0 and such that $K = \mathcal{F}k$ is

$$K(i\omega) = \frac{d(i\omega)}{\delta(i\omega)},$$
(2.2)

where $d(\cdot)$ and $\delta(\cdot)$ are polynomials such that $\deg d < \deg \delta$, and if $\delta(p) = 0$ for $p \in \mathbb{C}$ then Re p > 0, $|\operatorname{Im} p| < \Omega$.

Note that the class \mathcal{K} is quite wide: it consists of linear combinations of functions $q(t) e^{\lambda t} \mathbb{I}_{\{t \leq 0\}}$, where $\lambda \in \mathbb{C}$, Re $\lambda > 0$, $|\text{Im } \lambda| < \Omega$, and where q(t) is a polynomial.

Definition 2. Let $\widehat{\mathcal{K}}$ be the class of functions $\widehat{k} : \mathbf{R} \to \mathbf{R}$ such that k(t) = 0 for t < 0 and such that $K(\cdot) = \mathcal{L}\widehat{k} \in H^2 \cap H^{\infty}$.

We are going to study linear predictors in the form $\widehat{y}(t) = \int_{-\infty}^{t} \widehat{k}(t-s)x(s) \, ds$ for the processes $y(t) = \int_{t}^{+\infty} k(t-s)x(s) \, ds$, where $k \in \mathcal{K}$ and $\widehat{k} \in \widehat{K}$. The predictors use historical values of the currently observable process $x(\cdot)$.

Definition 3. Let $\mathcal{X} = \{x(\cdot)\}$ be a class of functions $x : \mathbf{R} \to \mathbf{C}$. Let $r \in [1, +\infty]$.

(i) We say that the class \mathcal{X} is L_r -predictable in the weak sense if, for any $k(\cdot) \in \mathcal{K}$, there exists a sequence $\{\widehat{k}_m(\cdot)\}_{m=1}^{+\infty} = \{\widehat{k}_m(\cdot, \mathcal{X}, k)\}_{m=1}^{+\infty} \subset \widehat{\mathcal{K}}$ such that

$$\|y - \widehat{y}_m\|_{L_x(\mathbf{R})} \to 0$$
 as $m \to +\infty \quad \forall x \in \mathcal{X}$,

where

$$y(t) \stackrel{\scriptscriptstyle \Delta}{=} \int_t^{+\infty} k(t-s)x(s) \,\mathrm{d}s, \qquad \widehat{y}_m(t) \stackrel{\scriptscriptstyle \Delta}{=} \int_{-\infty}^t \widehat{k}_m(t-s)x(s) \,\mathrm{d}s.$$

(ii) Let the set $\mathcal{F}(\mathcal{X}) \triangleq \{X = \mathcal{F}x, x \in \mathcal{X}\}$ be provided with a norm $\|\cdot\|$. We say that the class \mathcal{X} is L_r -predictable in the weak sense uniformly with respect to the norm $\|\cdot\|$, if, for any $k(\cdot) \in \mathcal{K}$ and $\varepsilon > 0$, there exists $\hat{k}(\cdot) = \hat{k}(\cdot, \mathcal{X}, k, \|\cdot\|, \varepsilon) \in \hat{\mathcal{K}}$ such that

$$\|y - \widehat{y}\|_{L_r(\mathbf{R})} \leqslant \varepsilon \|X\| \quad \forall x \in \mathcal{X}, \quad X = \mathcal{F}x$$

Here $y(\cdot)$ is the same as above, $\widehat{y}(t) \stackrel{\scriptscriptstyle \Delta}{=} \int_{-\infty}^{t} \widehat{k}(t-s)x(s) \, ds$.

We call functions $\hat{k}(\cdot)$ in definition 3 predictors or predicting kernels.

2

3. The main result

Let $\Omega > 0$ be the same as in the definition of \mathcal{K} , and let

$$\mathcal{X}_L \stackrel{\scriptscriptstyle \Delta}{=} \{ x(\cdot) \in L_2(\mathbf{R}) : X(\omega) = 0 \text{ if } |\omega| > \Omega, \ X = \mathcal{F}x \},\$$

$$\mathcal{X}_H \stackrel{\scriptscriptstyle \Delta}{=} \{ x(\cdot) \in L_2(\mathbf{R}) : X(\omega) = 0 \text{ if } |\omega| < \Omega, \ X = \mathcal{F}x \}.$$

In particular, \mathcal{X}_L is a class of band-limited processes and \mathcal{X}_H is a class of high-frequency processes.

3.1. Predictability of band-limited and high-frequency processes from L_2

Theorem 1.

- (i) The classes X_L and X_H are L_2 -predictable in the weak sense.
- (ii) The classes \mathcal{X}_L and \mathcal{X}_H are L_{∞} -predictable in the weak sense uniformly with respect to the norm $\|\cdot\|_{L_2(\mathbb{R})}$.
- (iii) For any q > 2, the classes \mathcal{X}_L and \mathcal{X}_H are L_2 -predictable in the weak sense uniformly with respect to the norm $\|\cdot\|_{L_q(\mathbf{R})}$.

Remark 1. Since the constant Ω is the same for the classes $\mathcal{K}, \mathcal{X}_L, \mathcal{X}_H$, the set of $k(\cdot) \in \mathcal{K}$ such that the corresponding processes $y(\cdot)$ can be predicted is restricted for $x(\cdot) \in \mathcal{X}_H$. On the other hand, these restrictions are absent for band-limited processes $x(\cdot) \in \mathcal{X}_L$, since they are automatically included in all similar classes with larger Ω , i.e., the constant Ω in the definition of \mathcal{X}_L can always be increased.

The question arises regarding how to find the predicting kernels. In the proof of theorem 1, a possible choice of the kernels is explicitly given via Fourier transforms.

3.2. Predictability for some bounded processes

Let $C(\mathbf{R})$ be the Banach space of all bounded and continuous functions $f : \mathbf{R} \to \mathbf{C}$, and let $C(\mathbf{R})^*$ be the dual space for $C(\mathbf{R})$, i.e., it is the space of all linear continuous functionals $\xi : C(\mathbf{R}) \to \mathbf{C}$ (see, e.g., Yosida (1980)).

Let \mathcal{M}_{∞} be the class of all processes $x(t) : \mathbf{R} \to \mathbf{C}$ such that there exist a function $X_c \in L_1(\mathbf{R})$, a sequence $\{\omega_k\}_{k=1}^{+\infty} \subset \mathbf{R}$ and a sequence $\{c_k\}_{k=1}^{+\infty} \subset \mathbf{C}$ such that $\sum_{k=1}^{+\infty} |c_k| < +\infty$ and

$$x(t) = \frac{1}{2\pi} \sum_{k=1}^{\infty} c_k \operatorname{e}^{\mathrm{i}\omega_k t} + \frac{1}{2\pi} \int_{-\infty}^{+\infty} \operatorname{e}^{\mathrm{i}\omega t} X_c(\omega) \,\mathrm{d}\omega.$$

Clearly, any set $X \stackrel{\scriptscriptstyle \Delta}{=} (\{\omega_k\}_{k=1}^{+\infty}, \{c_k\}_{k=1}^{+\infty}, X_c)$ with the required properties is uniquely defined by the process $x \in \mathcal{M}_{\infty}$ and can be associated with a unique element of $C(\mathbf{R})^*$ such that

$$\langle f, X \rangle = \sum_{k=1}^{\infty} c_k f(\omega_k) + \int_{-\infty}^{+\infty} f(\omega) X_c(\omega) \, \mathrm{d}\omega \quad \forall f \in C(\mathbf{R}).$$

In particular, $x(t) = \langle \frac{1}{2\pi} e^{it}, X \rangle$ for all *t*. We will denote this relationship as $X = \mathcal{F}x$, using the same notation as for the Fourier transform, and we extend definition 3 on this case (it is a frequency representation, but not a Fourier transform anymore). As required in definition 3, we provide the set $\{X\}$ of these sets *X* with the norm $\|\cdot\|_{C(\mathbf{R})^*}$.

If $x \in \mathcal{M}_{\infty}$, then $|x(t)| \leq (2\pi)^{-1} ||e^{it \cdot}||_{C(\mathbf{R})} ||X||_{C(\mathbf{R})^*}$. Hence all functions from \mathcal{M}_{∞} are bounded on **R**.

Let $\varepsilon \in (0, \Omega)$ be given. Let

 $\mathcal{M}_L \stackrel{\scriptscriptstyle \Delta}{=} \{ x \in \mathcal{M}_\infty : |\omega_k| \leqslant \Omega - \varepsilon(\forall k), \text{ supp } X_c \subseteq [-\Omega + \varepsilon, \Omega - \varepsilon] \},\$

 $\mathcal{M}_{H} \stackrel{\scriptscriptstyle \Delta}{=} \{ x \in \mathcal{M}_{\infty} : |\omega_{k}| \ge \Omega + \varepsilon (\forall k), \text{ supp } X_{\varepsilon} \subseteq (-\infty, -\Omega - \varepsilon] \cup [\Omega + \varepsilon, +\infty) \}.$

 \mathcal{M}_L is a class of band-limited processes and \mathcal{M}_H is a class of high-frequency processes.

Theorem 2. The classes \mathcal{M}_L and \mathcal{M}_H are L_{∞} -predictable in the weak sense uniformly with respect to the norm $\|\cdot\|_{C(\mathbf{R})^*}$.

4. On a model with an ideal low-pass filter

Corollary 1. Assume a model with a process $x(\cdot)$ such that an observer is able to decompose it as $x(t) = x_L(t) + x_H(t)$, where $x_L(\cdot) \in \mathcal{X}_L \cup \mathcal{M}_L$ and $x_H(\cdot) \in \mathcal{X}_H \cup \mathcal{M}_H$. Then this observer would be able to predict (approximately, in the sense of weak predictability) the values of $y(t) = \int_t^{+\infty} k(t-s)x(s) \, ds$ for $k(\cdot) \in \mathcal{K}$ by predicting the processes $y_L(t) = \int_t^{+\infty} k(t-s)x_L(s) \, ds$ and $y_H(t) = \int_t^{+\infty} k(t-s)x_H(s) \, ds$ separately. More precisely, the process $\hat{y}(t) \triangleq \hat{y}_L(t) + \hat{y}_H(t)$ is the prediction of y(t), where $y_L(t) = \int_{-\infty}^t \hat{k}_L(t-s)x_L(s) \, ds$ and $y_H(t) = \int_{-\infty}^t \hat{k}_H(t-s)x_H(s) \, ds$, and where $\hat{k}_L(\cdot)$ and $\hat{k}_H(\cdot)$ are predicting kernels whose existence for the processes $x_L(\cdot)$ and $x_H(\cdot)$ is established above.

Let $\chi_L(\omega) \stackrel{\scriptscriptstyle \Delta}{=} \mathbb{I}_{\{|\omega| \leq \Omega\}}$ and $\chi_H(\omega) \stackrel{\scriptscriptstyle \Delta}{=} 1 - \chi_L(\omega) = \mathbb{I}_{\{|\omega| > \Omega\}}$, where $\omega \in \mathbf{R}$.

The assumptions of corollary 1 mean that there are a low-pass filter and a high-pass filter with the transfer functions χ_L and χ_H , respectively, with $x(\cdot)$ as the input, i.e., that the values $x_L(s)$ and $x_H(s)$ for $s \leq t$ are available at time *t*, where

$$x_L(\cdot) \stackrel{\scriptscriptstyle \Delta}{=} \mathcal{F}^{-1}X_L, \quad X_L(\omega) \stackrel{\scriptscriptstyle \Delta}{=} \chi_L(\omega)X(\omega), \quad x_H(\cdot) \stackrel{\scriptscriptstyle \Delta}{=} \mathcal{F}^{-1}X_H, \quad X_H(\omega) \stackrel{\scriptscriptstyle \Delta}{=} \chi_H(\omega)X(\omega),$$

and where $X \triangleq \mathcal{F}x$. It follows that the predictability in the weak sense described in definition 3 is possible for any process $x(\cdot)$ that can be decomposed without error on a band-limited process and a high-frequency process, i.e., when there is a low-pass filter which behaves as an ideal filter for this process. (Since $x_H(t) = x(t) - x_L(t)$, the existence of the low-pass filter implies the existence of the high-pass filter). On the other hand, corollary 1 implies that the existence of ideal low-pass filters is impossible for general processes, since they cannot be predictable in the sense of definition 3.

Clearly, processes $x(\cdot) \in \mathcal{X}_L \cup \mathcal{X}_H \cup \mathcal{M}_L \cup \mathcal{M}_H$ are automatically covered by corollary 1, i.e., the existence of the filters is not required for this case. For instance, we have immediately that $x_L(\cdot) = x(\cdot)$ and $x_H(\cdot) \equiv 0$ for band-limited processes.

5. Proofs

Let $k(\cdot) \in \mathcal{K}$ and $K(i\omega) = \mathcal{F}k$. Let (2.2) holds with $\delta(p) = \prod_{m=1}^{n} \delta_m(p)$, where $\delta_m(p) \triangleq p - a_m + b_m i$, and where $a_m, b_m \in \mathbf{R}, p \in \mathbf{C}$. By the assumptions on \mathcal{K} , we have that $a_m > 0$ and $|b_m| < \Omega$.

It suffices to present a set of predicting kernels \hat{k} with the desired properties. We will use a version of the construction introduced in Dokuchaev (1996) for an optimal control problem. This construction is very straightforward and does not use the advanced theory of H^p -spaces. For $\gamma \in \mathbf{R}$, set

$$\alpha_m = \frac{\Omega^2 - b_m^2}{a_m}, \qquad V_m(p) \stackrel{\scriptscriptstyle \Delta}{=} 1 - \exp\left(\gamma \frac{p - a_m + b_m i}{p + \alpha_m - b_m i}\right), \qquad V(p) \stackrel{\scriptscriptstyle \Delta}{=} \prod_{m=1}^n V_m(p),$$

 $\widehat{K}(\mathrm{i}\omega) \stackrel{\scriptscriptstyle \Delta}{=} V(\mathrm{i}\omega)K(\mathrm{i}\omega).$

Lemma 1.

- (i) $V(p) \in H^2 \cap H^\infty$ and $\widehat{K}(p) \stackrel{\wedge}{=} K(p)V(p) \in H^2 \cap H^\infty$:
- (ii) If $\gamma > 0$ and $\omega \in [-\Omega, \Omega]$, then $|V(i\omega)| \leq 1$. If $\gamma < 0$, and if $\omega \in \mathbf{R}$, $|\omega| \ge \Omega$, then $|V(i\omega)| \le 1$.
- (iii) If $\omega \in (-\Omega, \Omega)$, then $V(i\omega) \to 1$ as $\gamma \to +\infty$. If $\omega \in \mathbf{R}$ and $|\omega| > \Omega$, then $V(i\omega) \to 1$ as $\gamma \to -\infty$.
- (iv) For any $\varepsilon > 0$, $V(i\omega) \to 1$ as $\gamma \to +\infty$ uniformly in $\omega \in [-\Omega + \varepsilon, \Omega \varepsilon]$ as $\gamma \to +\infty$, and $V(i\omega) \to 1$ as $\gamma \to -\infty$ uniformly in $\omega \in \mathbf{R}$ such that $|\omega| \ge \Omega + \varepsilon$.

Proof of lemma 1. Clearly, $V_m(p) \in H^{\infty}$, and $\delta_m(p)^{-1}V_m(p) \in H^2 \cap H^{\infty}$, since the pole of $\delta_m(p)^{-1}$ is being compensated by multiplying on $V_m(p)$. It follows that $K(p)V(p) \in H^2 \cap H^{\infty}$. Then statement (i) follows.

Further, for $\omega \in \mathbf{R}$,

$$\frac{\mathrm{i}\omega - a_m + b_m i}{\mathrm{i}\omega + \alpha_m - b_m i} = \frac{(-a_m + \mathrm{i}\omega + ib_m)(\alpha_m - \mathrm{i}\omega + b_m i)}{(\omega - b_m)^2 + a_m^2}$$
$$= \frac{-a_m \alpha_m + (\omega + b_m)(\omega - b_m)}{(\omega - b_m)^2 + \alpha_m^2} + \mathrm{i}\frac{-a_m(\omega + b_m) + \alpha_m(\omega + b_m)}{(\omega - b_m)^2 + \alpha_m^2}.$$

Then,

$$\operatorname{Re}\frac{\mathrm{i}\omega - a_m + b_m i}{\mathrm{i}\omega + \alpha_m - b_m i} = \frac{-a_m \alpha_m + \omega^2 - b_m^2}{(\omega - b_m)^2 + \alpha_m^2} = \frac{\omega^2 - \Omega^2}{(\omega - b_m)^2 + \alpha_m^2}$$

Then statements (ii)–(iv) follow. This completes the proof of lemma 1.

Proof of theorem 1. For $x(\cdot) \in L_2(\mathbf{R})$, let $X \stackrel{\scriptscriptstyle \Delta}{=} \mathcal{F}x$, $Y \stackrel{\scriptscriptstyle \Delta}{=} \mathcal{F}y = K(i\omega)X(\omega)$. Let V be as defined above. Set $\widehat{Y}(\omega) \stackrel{\scriptscriptstyle \Delta}{=} \widehat{K}(i\omega)X(\omega) = V(i\omega)Y(\omega)$.

Let us consider the cases of \mathcal{X}_L and \mathcal{X}_H simultaneously. For the case of the class \mathcal{X}_L , consider $\gamma > 0$ and assume that $\gamma > 0$ and $\gamma \to +\infty$. Set $D \stackrel{\scriptscriptstyle \Delta}{=} [-\Omega, \Omega]$ for this case. For the case of the class \mathcal{X}_H , consider $\gamma < 0$ and assume that $\gamma < 0$ and $\gamma \to -\infty$. Set $D \stackrel{\scriptscriptstyle \Delta}{=} (-\infty, -\Omega] \cup [\Omega, +\infty)$ for this case.

Let $x(\cdot) \in \mathcal{X}_L$ or $x(\cdot) \in \mathcal{X}_H$. In both cases, lemma 1 gives that $|V(i\omega)| \leq 1$ for all $\omega \in D$. If $\gamma \to +\infty$ or $\gamma \to -\infty$ respectively for \mathcal{X}_L or \mathcal{X}_H cases, then $V(i\omega) \to 1$ for a.e. $\omega \in D$, i.e., for a.e. ω such that $X(\omega) \neq 0$.

Let us prove (i). Since $K(i\omega) \in L_{\infty}(\mathbb{R})$ and $X \in L_2(\mathbb{R})$, we have that $Y(\omega) = K(i\omega)X(\omega) \in L_2(\mathbb{R})$ and $\widehat{Y} \in L_2(\mathbb{R})$. By lemma 1, it follows that

$$\widehat{Y}(\omega) \to Y(\omega) \quad \text{for a.e.} \quad \omega \in \mathbf{R},$$
(5.1)

as $\gamma \to +\infty$ or $\gamma \to -\infty$ respectively for \mathcal{X}_L or \mathcal{X}_H cases. We have that $X \in L_2(\mathbf{R}), K(i\omega) \in L_2(\mathbf{R}) \cap L_\infty(\mathbf{R})$ and

$$|\widehat{K}(i\omega) - K(i\omega)| \leq |V(i\omega) - 1| |K(i\omega)| \leq 2|K(i\omega)|, \qquad \omega \in D,$$
(5.2)

$$|\widehat{Y}(\omega) - Y(\omega)| \leq 2|Y(\omega)| = 2|K(i\omega)||X(\omega)|, \qquad \omega \in D.$$
(5.3)

5

By (5.1), (5.3) and by the Lebesque dominance theorem, it follows that

$$\|\widehat{Y} - Y\|_{L_2(\mathbf{R})} \to 0, \quad \text{i.e.,} \quad \|\widehat{y} - y\|_{L_2(\mathbf{R})} \to 0,$$
 (5.4)

as $\gamma \to +\infty$ or $\gamma \to -\infty$ respectively for \mathcal{X}_L or \mathcal{X}_H cases, where $\widehat{y} = \mathcal{F}^{-1}\widehat{Y}$.

Let us prove (ii)–(iii). Take d = 1 for (ii) and take d = 2 for (iii). If $X \in L_q(\mathbf{R})$ for q > d, then Hölder inequality gives

$$\|Y - Y\|_{L_d(\mathbf{R})} \leq \|K(i\omega) - K(i\omega)\|_{L_\mu(D)} \|X\|_{L_q(D)},$$
(5.5)

where μ is such that $1/\mu + 1/q = 1/d$. By (5.2) and by the Lebesque dominance theorem again, it follows that

$$\|\widehat{K}(\mathrm{i}\omega) - K(\mathrm{i}\omega)\|_{L_{\mu}(D)} \to 0 \quad \forall \mu \in [1, +\infty),$$
(5.6)

as $\gamma \to +\infty$ or $\gamma \to -\infty$ respectively for \mathcal{X}_L or \mathcal{X}_H cases. By (5.5) and (5.6), it follows that the predicting kernels $\hat{k}(\cdot) = \hat{k}(\cdot, \gamma) = \mathcal{F}^{-1}\hat{K}(i\omega)$ are as required in statements (ii)–(iii). This completes the proof of theorem 1.

Proof of theorem 2. For $x(\cdot) \in \mathcal{M}_{\infty}$ such that $X = (\{\omega_k\}_{k=1}^{+\infty}, \{c_k\}_{k=1}^{+\infty}, X_c)$, we have that the corresponding set $Y = \mathcal{F}y$ is $Y = (\{\omega_k\}_{k=1}^{+\infty}, \{K(i\omega_k)c_k\}_{k=1}^{+\infty}, K(i\omega)X_c(\omega))$. Similarly to X, it can be considered as element of $C(\mathbf{R})^*$ such that $y(t) = \langle \frac{1}{2\pi} e^{it}, Y \rangle$. Let V and \widehat{K} be as defined above. Set

$$\widehat{Y} \stackrel{\scriptscriptstyle \Delta}{=} \left(\{ \omega_k \}_{k=1}^{+\infty}, \{ \widehat{K}(\mathrm{i}\omega_k)c_k \}_{k=1}^{+\infty}, \, \widehat{K}(\mathrm{i}\omega)X_c(\omega) \right)$$

It can be seen as an element of $C(R)^*$, and $\widehat{y}(t) = \int_{-\infty}^t \widehat{k}(t-s)x(s) \, ds = \langle \frac{1}{2\pi} e^{it}, \widehat{Y} \rangle$, where the kernel is defined via the inverse Fourier transform $\widehat{k}(\cdot) = \mathcal{F}^{-1}\widehat{K}(i\omega)$.

We consider the cases of \mathcal{M}_L and \mathcal{M}_H simultaneously. For the case of the class \mathcal{M}_L , we consider $\gamma > 0$ and $\gamma \to +\infty$. Set $D_{\varepsilon} \triangleq [-\Omega + \varepsilon, \Omega - \varepsilon]$ for this case. For the case of the class \mathcal{M}_H , we consider $\gamma < 0$ and $\gamma \to -\infty$. Set $D_{\varepsilon} \triangleq (-\infty, -\Omega - \varepsilon] \cup [\Omega + \varepsilon, +\infty)$ for this case.

Let $x(\cdot) \in \mathcal{M}_L$ or $x(\cdot) \in \mathcal{M}_H$. In both cases, lemma 1 gives that $|V(i\omega)| \leq 1$ for all $\omega \in D_{\varepsilon}$. If $\gamma \to +\infty$ or $\gamma \to -\infty$ respectively for \mathcal{M}_L or \mathcal{M}_H cases, then $V(i\omega) \to 1$ uniformly in $\omega \in D_{\varepsilon}$. Hence $\|\widehat{K} - K\|_{L_{\infty}(D_{\varepsilon})} \to 0$ as $\gamma \to +\infty$ or $\gamma \to -\infty$, for the cases of \mathcal{M}_L and \mathcal{M}_H , respectively. If $x \in \mathcal{M}_L$ or $x \in \mathcal{M}_H$, then

$$|\langle f, X \rangle| \leq \max_{t \in D_{\varepsilon}} |f(t)| ||X||_{C(\mathbf{R})^*} \quad \forall f \in C(\mathbf{R}), \quad X = \mathcal{F}x.$$

Hence,

$$\left|\widehat{y}(t) - y(t)\right| = \left|\left\langle\frac{1}{2\pi}e^{it}, \widehat{Y} - Y\right\rangle\right| = \left|\left\langle\frac{1}{2\pi}e^{it}, \widehat{K} - K\right\rangle, X\right\rangle\right| \leq \frac{1}{2\pi} \|\widehat{K} - K\|_{L_{\infty}(D_{\varepsilon})}\|X\|_{C(\mathbf{R})^{*}}$$
for all $t \in \mathbf{R}$. Then the proof of theorem 2 follows.

Corollary 1 follows immediately from theorem 1.

Remark 2. Formally, the corresponding predictors require the past values of x(s) for all $s \in (-\infty, t]$, but it is not too restrictive, since $\int_{-\infty}^{t} \hat{k}(t-s)x(s) ds$ can be approximated by $\int_{-M}^{t} \hat{k}(t-s)x(s) ds$ for large enough M > 0. In addition, the corresponding transfer functions can be approximated by rational fraction polynomials, and more general kernels k can be approximated by kernels from \mathcal{K} .

Remark 3. The system for the suggested predictors is stable, since the corresponding transfer functions have poles in the domain {Re z < 0} only. However, the suggested predictors are

7

not robust. For instance, if the predictor is designed for the class \mathcal{X}_L and applied to a process $x(\cdot) \notin \mathcal{X}_L$ with small nonzero energy at the frequencies outside $[-\Omega, \Omega]$, then the error generated by the presence of this energy increases if $\gamma \to \infty$.

References

Beutler F G 1966 Error-free recovery of signals from irregularly spaced samples SIAM Rev. 8 328–35

Brown J R Jr 1969 Bounds for truncation error in sampling expansion of band-limited signals *IEEE Trans. Inf. Theory* **15** 440–4

Dokuchaev N G 1996 Suboptimal damping of forced oscillations *Vestnik St. Petersburg Univ.: Math.* **29** 49–51 Duren P 1970 *Theory of H^p-Spaces* (New York: Academic)

Knab J J 1979 Interpolation of band-limited functions using the approximate prolate series *IEEE Trans. Inf. Theory* **25** 717–20

Lyman R J, Edmonson W W, McCullough S and Rao M 2000 The predictability of continuous-time, band limited processes *IEEE Trans. Signal Process.* **48** 311–6

Lyman R J and Edmonson W W 2001 Linear prediction of band limited processes with flat spectral densities *IEEE Trans. Signal Process.* **49** 1564–9

Marvasti F 1986 Comments on 'A note on the predictability of band-limited processes' *Proc. IEEE* **74** 1596 Papoulis A 1985 A note on the predictability of band-limited processes *Proc. IEEE* **73** 1332–3

Slepian D 1978 Prolate spheroidal wave functions, Fourier analysis, and uncertainty: V. The discrete case Bell Syst. Tech. J. 57 1371–430

Vaidyanathan P P 1987 On predicting a band-limited signal based on past sample values *Proc. IEEE* **75** 1125–7 Wainstein L A and Zubakov V D 1962 *Extraction of Signals from Noise* (Englewood Cliffs, NJ: Prentice-Hall) Yosida K 1980 *Functional Analysis* (New York: Springer)